

**Product Manual** 

# Barracuda® 7200.9 Serial ATA

ST3200827AS
ST3160812AS
ST3160212AS
ST3120813AS
ST3120213AS
ST3808110AS
ST3802110AS
ST3402111AS

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ST3250624AS

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One gigabyte, or GB, equals one billion bytes when referring to hard drive capacity. Accessible capacity may vary depending on operating environment and formatting. Quantitative usage examples for various applications are for illustrative purposes. Actual quantities will vary based on various factors, including file size, file format, features and application software. Seagate reserves the right to change, without notice, product offerings or specifications.

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## 1.0 Introduction

This manual describes the functional, mechanical and interface specifications for the following Seagate Barracuda® 7200.9 Serial ATA model drives:

ST3500841AS	ST3320633AS	ST3200827AS	ST3120213AS
ST3500641AS	ST3300822AS	ST3160812AS	ST3802110AS
ST3400833AS	ST3300622AS	ST3160212AS	ST3808110AS
ST3400633AS	ST3250824AS	ST3120813AS	ST3402111AS
ST3320833AS	ST3250624AS		

These drives provide the following key features:

- 7,200 RPM spindle speed.
- High instantaneous (burst) data-transfer rates (up to 300 Mbytes per second).
- Tunneling Magnetoresistive (TMR) recording heads provide the drives with increased areal density.
- State-of-the-art cache and on-the-fly error-correction algorithms.
- Native Command Queueing with command ordering to increase performance in demanding applications.
- Full-track multiple-sector transfer capability without local processor intervention.
- Quiet operation.
- 350 Gs nonoperating shock.
- SeaTools diagnostic software performs a drive self-test that eliminates unnecessary drive returns.
- Support for S.M.A.R.T. drive monitoring and reporting.
- Supports latching SATA cables and connectors.

#### 1.1 About the Serial ATA interface

The Serial ATA interface provides several advantages over the traditional (parallel) ATA interface. The primary advantages include:

- Easy installation and configuration with true plug-and-play connectivity. It is not necessary to set any jumpers or other configuration options.
- Thinner and more flexible cabling for improved enclosure airflow and ease of installation.
- Scalability to higher performance levels.

In addition, Serial ATA makes the transition from parallel ATA easy by providing legacy software support. Serial ATA was designed to allow you to install a Serial ATA host adapter and Serial ATA disc drive in your current system and expect all of your existing applications to work as normal.

The Serial ATA interface connects each disc drive in a point-to-point configuration with the Serial ATA host adapter. There is no master/slave relationship with Serial ATA devices like there is with parallel ATA. If two drives are attached on one Serial ATA host adapter, the host operating system views the two devices as if they were both "masters" on two separate ports. This essentially means both drives behave as if they are Device 0 (master) devices.

**Note.** The host adapter may, optionally, emulate a master/slave environment to host software where two devices on separate Serial ATA ports are represented to host software as a Device 0 (master) and Device 1 (slave) accessed at the same set of host bus addresses. A host adapter that emulates a master/slave environment manages two sets of shadow registers. This is not a typical Serial ATA environment.

The Serial ATA host adapter and drive share the function of emulating parallel ATA device behavior to provide backward compatibility with existing host systems and software. The Command and Control Block registers, PIO and DMA data transfers, resets, and interrupts are all emulated.

The Serial ATA host adapter contains a set of registers that shadow the contents of the traditional device registers, referred to as the Shadow Register Block. All Serial ATA devices behave like Device 0 devices. For additional information about how Serial ATA emulates parallel ATA, refer to the "Serial ATA: High Speed Serialized AT Attachment" specification. The specification can be downloaded from www.serialata.org.

## 2.0 Drive specifications

Unless otherwise noted, all specifications are measured under ambient conditions, at 25°C, and nominal power. For convenience, the phrases *the drive* and *this drive* are used throughout this manual to indicate the following drive models:

ST3500841AS	ST3320633AS	ST3200827AS	ST3120213AS
ST3500641AS	ST3300822AS	ST3160812AS	ST3802110AS
ST3400833AS	ST3300622AS	ST3160212AS	ST3808110AS
ST3400633AS	ST3250824AS	ST3120813AS	ST3402111AS
ST3320833AS	ST3250624AS		

## 2.1 Specification summary tables

The specifications listed in the following table are for quick reference. For details on specification measurement or definition, see the appropriate section of this manual.

Table 1: Drive specifications summary for 500 Gbyte models

Drive specification	ST3500841AS	ST3500641AS	
Formatted Gbytes (512 bytes/sector)*	500		
Guaranteed sectors	976,773,168		
Bytes per sector	512		
Default sectors per track	63		
Default read/write heads	16		
Default cylinders	16,383		
Recording density, KBPI (kbits/in max)	790.1		
Track density, KTPI (ktracks/in avg.)	124.5		
Areal density, (Gbits/in <sup>2</sup> avg)	97.96		
Spindle speed (RPM)	7,200		
Internal data transfer rate (Mbits/sec max)	815.2		
Sustained data transfer rate OD (Mbytes/sec max)	65		
I/O data-transfer rate (Mbytes/sec max)	300		
ATA data-transfer modes supported	PIO modes 0–4 Multiword DMA modes 0–2 Ultra DMA modes 0–6		
Cache buffer	8 Mbytes	16 Mbytes	
Height (mm max)	26.1 mm (1.028 inches)	•	
Width (mm max)	101.6 mm (4.000 inches) +/	/- 0.010 inches	
Length (mm max)	146.99 mm (5.787 inches)		
Weight (max)	710 grams (1.57 lb.)		
Average latency (msec)	4.16		
Power-on to ready (sec max)	13.0 sec		
Standby to ready (sec max)	13.0 sec	13.0 sec	
Track-to-track seek time (msec typical)	<0.8 read; <1.0 write	<0.8 read; <1.0 write	
Average seek, read (msec typical)	<8.2		
Average seek, write (msec typical)	<9.0	<9.0	
Startup current (typical) 12V (peak)	2.9 amps	2.9 amps	
Voltage tolerance (including noise)	5V ± 5% 12V ± 10%		
Ambient temperature	0° to 60°C (operating) -40° to 70°C (nonoperating	)	
Temperature gradient (°C per hour max)	20°C (operating) 30°C (nonoperating)		
Relative humidity	5% to 90% (operating) 5% to 95% (nonoperating)		
Relative humidity gradient	30% per hour max		
Wet bulb temperature (°C max)	37.7 (operating) 40.0 (nonoperating)		
Altitude, operating	-60.96 m to 3,048 m (-200 ft. to 10,000+ ft.)		
Altitude, nonoperating (below mean sea level, max)	-60.96 m to 12,192 m (-200 ft. to 40,000+ ft.)		
Operational Shock (max at 2 msec)	63 Gs		
Non-Operational Shock (max at 2 msec)	300 Gs		
Vibration, operating	5–22 Hz: 0.25 Gs, Limited displacement 22–350 Hz: 0.5 Gs 350–500 Hz:: 0.25 Gs		

Drive specification	ST3500841AS	ST3500641AS	
Vibration, nonoperating	5–22 Hz: 0.25 Gs, Limited 22–350 Hz: 5.0 Gs 350–500 Hz:: 1.0 Gs	displacement	
Drive acoustics, sound power (bels)			
Idle**	2.8 (typical) 3.0 (max)		
Performance seek	3.7 (typical) 3.9 (max)		
Nonrecoverable read errors	1 per 10 <sup>14</sup> bits read	1 per 10 <sup>14</sup> bits read	
Annualized Failure Rate (AFR)	0.34%	0.34%	
Warranty	To determine the warranty access the following web p www.seagate.com/support From this page, click on the to provide the drive serial in	5 years on distribution units. To determine the warranty for a specific drive, use a web browser to access the following web page: www.seagate.com/support/service/ From this page, click on the "Verify Your Warranty" link. You will be asked to provide the drive serial number, model number (or part number) and country of purchase. The system will display the warranty information for your drive.	
Contact start-stop cycles (25°C, 50% rel. humidity)	50,000	50,000	
Supports Hotplug operation per SATA II specification	Yes	Yes	

<sup>\*</sup>One Gbyte equals one billion bytes when referring to hard drive capacity. Accessible capacity may vary depending on operating environment and formatting.

<sup>\*\*</sup>During periods of drive idle, some offline activity may occur according to the S.M.A.R.T. specification, which may increase acoustic and power to operational levels.

Table 2: Drive specifications summary for 400 Gbyte models

Drive specification	ST3400633AS	ST3400833AS	
Formatted Gbytes (512 bytes/sector)*	400		
Guaranteed sectors	781,422,768		
Bytes per sector	512		
Default sectors per track	63		
Default read/write heads	16		
Default cylinders	16,383		
Recording density, KBPI (kbits/in max)	790.1		
Track density, KTPI (ktracks/in avg.)	124.5		
Areal density, (Gbits/in <sup>2</sup> avg)	97.96		
Spindle speed (RPM)	7,200		
Internal data transfer rate (Mbits/sec max)	815.2		
Sustained data transfer rate OD (Mbytes/sec max)	65		
I/O data-transfer rate (Mbytes/sec max)	300		
ATA data-transfer modes supported	PIO modes 0–4 Multiword DMA modes 0–2 Ultra DMA modes 0–6		
Cache buffer	16 Mbytes	8 Mbytes	
Height (mm max)	26.1 mm (1.028 inches)		
Width (mm max)	101.6 mm (4.000 inches) +/- 0.010 inc	ches	
Length (mm max)	146.99 mm (5.787 inches)		
Weight (max)	710 grams (1.57 lb.)		
Average latency (msec)	4.16	4.16	
Power-on to ready (sec max)	13.0 sec		
Standby to ready (sec max)	13.0 sec		
Track-to-track seek time (msec typical)	<0.8 (read), <1.0 (write)		
Average seek, read (msec typical)	<8.2		
Average seek, write (msec typical)	<9.0		
Startup current (typical) 12V (peak)	2.9 amps		
Voltage tolerance (including noise)	5V ± 5% 12V ± 10%		
Ambient temperature	0° to 60°C (operating) -40° to 70°C (nonoperating)		
Temperature gradient (°C per hour max)	20°C (operating) 30°C (nonoperating)		
Relative humidity	5% to 90% (operating) 5% to 95% (nonoperating)		
Relative humidity gradient	30% per hour max		
Wet bulb temperature (°C max)	37.7 (operating) 40.0 (nonoperating)		
Altitude, operating	-60.96 m to 3,048 m (-200 ft. to 10,000+ ft.)		
Altitude, nonoperating (below mean sea level, max)	-60.96 m to 12,192 m (-200 ft. to 40,000+ ft.)		
Operational Shock (Gs max at 2 msec)	63		
Non-Operational Shock (Gs max at 2 msec)	300 Gs		
Vibration, operating	5–22 Hz: 0.25 Gs, Limited displaceme 22–350 Hz: 0.5 Gs 350–500 Hz:: 0.25 Gs	ent	

Drive specification	ST3400633AS	ST3400833AS	
Vibration, nonoperating	5–22 Hz: 0.25 Gs, Limited displa 22–350 Hz: 5.0 Gs 350–500 Hz:: 1.0 Gs	acement	
Drive acoustics, sound power (bels)			
Idle**	2.8 (typical) 3.0 (max)		
Performance seek	3.7 (typical) 3.9 (max)		
Nonrecoverable read errors	1 per 10 <sup>14</sup> bits read	1 per 10 <sup>14</sup> bits read	
Annualized Failure Rate (AFR)	0.34%		
Warranty	the following web page: www.seagate.com/support/service From this page, click on the "Ver provide the drive serial number, r	specific drive, use a web browser to access ce/ rify Your Warranty" link. You will be asked to model number (or part number) and country play the warranty information for your drive.	
Contact start-stop cycles (25°C, 50% rel. humidity)	50,000		
Supports Hotplug operation per SATA II specification	Yes	Yes	

<sup>\*</sup>One Gbyte equals one billion bytes when referring to hard drive capacity. Accessible capacity may vary depending on operating environment and formatting.

<sup>\*\*</sup>During periods of drive idle, some offline activity may occur according to the S.M.A.R.T. specification, which may increase acoustic and power to operational levels.

Table 3: Drive specifications summary for 320 Gbyte models

Drive specification	ST3320833AS	ST3320633AS	
Formatted Gbytes (512 bytes/sector)*	320		
Guaranteed sectors	625,142,448		
Bytes per sector	512		
Default sectors per track	63		
Default read/write heads	16		
Default cylinders	16,383		
Recording density, KBPI (kbits/in max)	790.1		
Track density, KTPI (ktracks/in avg.)	124.5		
Areal density, (Gbits/in <sup>2</sup> avg)	97.96		
Spindle speed (RPM)	7,200		
Internal data transfer rate (Mbits/sec max)	867.2		
Sustained data transfer rate OD (Mbytes/sec max)	76.6		
I/O data-transfer rate (Mbytes/sec max)	300		
ATA data-transfer modes supported	PIO modes 0–4 Multiword DMA modes 0–2 Ultra DMA modes 0–6		
Cache buffer	8 Mbytes	16 Mbytes	
Height (mm max)	26.1 mm (1.028 inches)	·	
Width (mm max)	101.6 mm (4.000 inches) +/- 0	.010 inches	
Length (mm max)	146.99 mm (5.787 inches)		
Weight (max)	655 grams (1.44 lb.)	655 grams (1.44 lb.)	
Average latency (msec)	4.16	4.16	
Power-on to ready (sec max)	11.0 sec		
Standby to ready (sec max)	11.0 sec		
Track-to-track seek time (msec typical)	<0.8 (read), <1.0 (write)		
Average seek, read (msec typical)	<8.0		
Average seek, write (msec typical)	<9.0		
Startup current (typical) 12V (peak)	2.8 amps		
Voltage tolerance (including noise)	5V ± 5% 12V ± 10%		
Ambient temperature	0° to 60°C (operating) -40° to 70°C (nonoperating)		
Temperature gradient (°C per hour max)	20°C (operating) 30°C (nonoperating)		
Relative humidity	5% to 90% (operating) 5% to 95% (nonoperating)		
Relative humidity gradient	30% per hour max		
Wet bulb temperature (°C max)	37.7 (operating) 40.0 (nonoperating)		
Altitude, operating	-60.96 m to 3,048 m (-200 ft. to 10,000+ ft.)		
Altitude, nonoperating (below mean sea level, max)	-60.96 m to 12,192 m (-200 ft. to 40,000+ ft.)		
Operational Shock (Gs max at 2 msec)	63		
Non-Operational Shock (Gs max at 2 msec)	300 Gs		
Vibration, operating	5–22 Hz: 0.25 Gs, Limited disp 22–350 Hz: 0.5 Gs 350–500 Hz:: 0.25 Gs	olacement	

Drive specification	ST3320833AS	ST3320633AS
Vibration, nonoperating	5–22 Hz: 0.25 Gs, Limited dis 22–350 Hz: 5.0 Gs 350–500 Hz:: 1.0 Gs	splacement
Drive acoustics, sound power (bels)		
Idle**	2.7 (typical) 2.9 (max)	
Performance seek	3.4 (typical) 3.6 (max)	
Nonrecoverable read errors	1 per 10 <sup>14</sup> bits read	
Annualized Failure Rate (AFR)	0.34%	
Warranty	access the following web pag www.seagate.com/support/se From this page, click on the "\ to provide the drive serial nur	
Contact start-stop cycles (25°C, 50% rel. humidity)	50,000	
Supports Hotplug operation per SATA II specification	Yes	

Table 4: Drive specifications summary for 300 Gbyte models

Drive specification	ST3300822AS	ST3300622AS	
Formatted Gbytes (512 bytes/sector)*	300		
Guaranteed sectors	586,072,368		
Bytes per sector	512		
Default sectors per track	63		
Default read/write heads	16		
Default cylinders	16,383		
Recording density, KBPI (kbits/in max)	790.1		
Track density, KTPI (ktracks/in avg.)	124.5		
Areal density, (Gbits/in <sup>2</sup> avg)	97.96		
Spindle speed (RPM)	7,200		
Internal data transfer rate (Mbits/sec max)	867.2		
Sustained data transfer rate OD (Mbytes/sec max)	76.6		
I/O data-transfer rate (Mbytes/sec max)	300		
ATA data-transfer modes supported	PIO modes 0–4 Multiword DMA modes 0–2 Ultra DMA modes 0–6		
Cache buffer	8 Mbytes	16 Mbytes	
Height (mm max)	26.1 mm (1.028 inches)	·	
Width (mm max)	101.6 mm (4.000 inches) +/- 0.	.010 inches	
Length (mm max)	146.99 mm (5.787 inches)		
Weight (max)	655 grams (1.44 lb.)	655 grams (1.44 lb.)	
Average latency (msec)	4.16		
Power-on to ready (sec max)	11.0 sec		
Standby to ready (sec max)	11.0 sec		
Track-to-track seek time (msec typical)	<0.8 (read), <1.0 (write)		
Average seek, read (msec typical)	<8.0		
Average seek, write (msec typical)	<9.0		
Startup current (typical) 12V (peak)	2.8 amps		
Voltage tolerance (including noise)	5V ± 5% 12V ± 10%		
Ambient temperature	0° to 60°C (operating) -40° to 70°C (nonoperating)		
Temperature gradient (°C per hour max)	20°C (operating) 30°C (nonoperating)		
Relative humidity	5% to 90% (operating) 5% to 95% (nonoperating)		
Relative humidity gradient	30% per hour max		
Wet bulb temperature (°C max)	37.7 (operating) 40.0 (nonoperating)		
Altitude, operating	-60.96 m to 3,048 m (-200 ft. to 10,000+ ft.)		
Altitude, nonoperating (below mean sea level, max)	-60.96 m to 12,192 m (-200 ft. to 40,000+ ft.)		
Operational Shock (Gs max at 2 msec)	63	63	
Non-Operational Shock (Gs max at 2 msec)	300 Gs		
Vibration, operating	5–22 Hz: 0.25 Gs, Limited disp 22–350 Hz: 0.5 Gs 350–500 Hz:: 0.25 Gs	olacement	

Drive specification	ST3300822AS	ST3300622AS	
Vibration, nonoperating	5–22 Hz: 0.25 Gs, Limited of 22–350 Hz: 5.0 Gs 350–500 Hz:: 1.0 Gs	displacement	
Drive acoustics, sound power (bels)			
ldle**	2.7 (typical) 2.9 (max)		
Performance seek	3.4 (typical) 3.6 (max)		
Nonrecoverable read errors	1 per 10 <sup>14</sup> bits read		
Annualized Failure Rate (AFR)	0.34%		
Warranty	To determine the warranty for access the following web particular www.seagate.com/support/search to provide the drive serial numbers.	5 years on distribution units. To determine the warranty for a specific drive, use a web browser to access the following web page: www.seagate.com/support/service/ From this page, click on the "Verify Your Warranty" link. You will be asket to provide the drive serial number, model number (or part number) and country of purchase. The system will display the warranty information for your drive.	
Contact start-stop cycles (25°C, 50% rel. humidity)	50,000		
Supports Hotplug operation per SATA II specification	Yes	Yes	

<sup>\*</sup>One Gbyte equals one billion bytes when referring to hard drive capacity. Accessible capacity may vary depending on operating environment and formatting.

<sup>\*\*</sup>During periods of drive idle, some offline activity may occur according to the S.M.A.R.T. specification, which may increase acoustic and power to operational levels.

Table 5: Drive specifications summary for 250 and 200 Gbyte models

Drive specification	ST3250624AS	ST3250824AS	ST3200827AS
Formatted Gbytes (512 bytes/sector)*	250		200
Guaranteed sectors	488,397,168		390,721,968
Bytes per sector	512	512	
Default sectors per track	63		
Default read/write heads	16		
Default cylinders	16,383		
Recording density, KBPI (kbits/in max)	790.1		
Track density, KTPI (ktracks/in avg.)	124.5		
Areal density, (Gbits/in <sup>2</sup> avg)	97.96		
Spindle speed (RPM)	7,200		
Internal data transfer rate (Mbits/sec max)	867.2		
Sustained data transfer rate OD (Mbytes/sec max)	76.6		
I/O data-transfer rate (Mbytes/sec max)	300		
ATA data-transfer modes supported	PIO modes 0–4 Multiword DMA modes 0–3 Ultra DMA modes 0–6	2	
Cache buffer	16 Mbytes	8 Mbytes	
Height (mm max)	26.1 mm (1.028 inches)		
Width (mm max)	101.6 mm (4.000 inches) -	101.6 mm (4.000 inches) +/- 0.010 inches	
Length (mm max)	146.99 mm (5.787 inches)		
Weight (max)	580 grams (1.28 lb.)		
Average latency (msec)	4.16		
Power-on to ready (sec max)	11.0 sec		
Standby to ready (sec max)	11.0 sec		
Track-to-track seek time (msec typical)	<0.8 (read), <1.0 (write)		
Average seek, read (msec typical)	<8.0		
Average seek, write (msec typical)	<9.0		
Startup current (typical) 12V (peak)	2.8 amps		
Voltage tolerance (including noise)	5V ± 5% 12V ± 10%		
Ambient temperature	0° to 60°C (operating) -40° to 70°C (nonoperatin	g)	
Temperature gradient (°C per hour max)	20°C (operating) 30°C (nonoperating)		
Relative humidity	5% to 90% (operating) 5% to 95% (nonoperating)		
Relative humidity gradient	30% per hour max		
Wet bulb temperature (°C max)	37.7 (operating) 40.0 (nonoperating)		
Altitude, operating	-60.96 m to 3,048 m (-200 ft. to 10,000+ ft.)		
Altitude, nonoperating (below mean sea level, max)	-60.96 m to 12,192 m (-200 ft. to 40,000+ ft.)		
Operational Shock (Gs max at 2 msec)	63		
Non-Operational Shock (Gs max at 2 msec)	350 Gs		
Vibration, operating	5–22 Hz: 0.25 Gs, Limited displacement 22–350 Hz: 0.5 Gs 350–500 Hz:: 0.25 Gs		

Drive specification	ST3250624AS	ST3250824AS	ST3200827AS	
Vibration, nonoperating	5–22 Hz: 0.25 Gs, Lim 22–350 Hz: 5.0 Gs 350–500 Hz:: 1.0 Gs			
Drive acoustics, sound power (bels)				
ldle**	2.7 (typical) 2.9 (max)			
Performance seek	3.4 (typical) 3.6 (max)			
Nonrecoverable read errors	1 per 10 <sup>14</sup> bits read	1 per 10 <sup>14</sup> bits read		
Annualized Failure Rate (AFR)	0.34%	0.34%		
Warranty	To determine the warrathe following web page www.seagate.com/sup From this page, click of provide the drive serial	5 years on distribution units. To determine the warranty for a specific drive, use a web browser to access the following web page: www.seagate.com/support/service/ From this page, click on the "Verify Your Warranty" link. You will be asked to provide the drive serial number, model number (or part number) and country of purchase. The system will display the warranty information for your drive.		
Contact start-stop cycles (25°C, 50% rel. humidity)	50,000	50,000		
Supports Hotplug operation per SATA II specification	Yes	Yes		

<sup>\*</sup>One Gbyte equals one billion bytes when referring to hard drive capacity. Accessible capacity may vary depending on operating environment and formatting.

<sup>\*\*</sup>During periods of drive idle, some offline activity may occur according to the S.M.A.R.T. specification, which may increase acoustic and power to operational levels.

Table 6: Drive specifications summary for 160 Gbyte models

Drive specification	ST3160812AS	ST3160212AS
Formatted Gbytes (512 bytes/sector)*	160	
Guaranteed sectors	312,581,808	
Bytes per sector	512	
Default sectors per track	63	
Default read/write heads	16	
Default cylinders	16,383	
Recording density, KBPI (kbits/in max)	840.0	
Track density, KTPI (ktracks/in avg.)	141.5	
Areal density, (Gbits/in <sup>2</sup> avg)	119.0	
Spindle speed (RPM)	7,200	
Internal data transfer rate (Mbits/sec max)	867.2	
Sustained data transfer rate OD (Mbytes/sec max)	83	
I/O data-transfer rate (Mbytes/sec max)	300	
ATA data-transfer modes supported	PIO modes 0–4 Multiword DMA modes 0–2 Ultra DMA modes 0–6	
Cache buffer	8 Mbytes	2 Mbytes
Height (mm max)	26.1 mm (1.028 inches)	
Width (mm max)	101.6 mm (4.000 inches) +/- 0.010	inches
Length (mm max)	146.99 mm (5.787 inches)	
Weight (max)	580 grams (1.28 lb.)	
Average latency (msec)	4.16	
Power-on to ready (sec max)	<10.0 sec	
Standby to ready (sec max)	<10.0 sec	
Track-to-track seek time (msec typical)	<0.8 (read), <1.0 (write)	
Average seek, read (msec typical)	<8.0 (ST3160812AS & ST3160212AS models) <9.9 ( & models)	
Average seek, write (msec typical)	<9.0 (ST3160812AS & ST3160212AS models) <10.9 ( & models)	
Startup current (typical) 12V (peak)	2.8 amps	
Voltage tolerance (including noise)	5V ± 5% 12V ± 10%	
Ambient temperature	0° to 60°C (operating) -40° to 70°C (nonoperating)	
Temperature gradient (°C per hour max)	20°C (operating) 30°C (nonoperating)	
Relative humidity	5% to 90% (operating) 5% to 95% (nonoperating)	
Relative humidity gradient	30% per hour max	
Wet bulb temperature (°C max)	37.7 (operating) 40.0 (nonoperating)	
Altitude, operating	-60.96 m to 3,048 m (-200 ft. to 10,000+ ft.)	
Altitude, nonoperating (below mean sea level, max)	-60.96 m to 12,192 m (-200 ft. to 40,000+ ft.)	
Operational Shock (Gs max at 2 msec)	63	
Non-Operational Shock (Gs max at 2 msec)	350 Gs	

Drive specification	ST3160812AS	ST3160212AS	
Vibration, operating	5–22 Hz: 0.25 Gs, Limited 22–350 Hz: 0.5 Gs 350–500 Hz:: 0.25 Gs	displacement	
Vibration, nonoperating	5–22 Hz: 0.25 Gs, Limited 22–350 Hz: 5.0 Gs 350–500 Hz:: 1.0 Gs	displacement	
Drive acoustics, sound power (bels)			
Idle**	2.5 (typical) 2.7 (max)	2.5 (typical) 2.7 (max)	
Performance seek	3.3 (typical) 3.5 (max)	3.3 (typical) 3.5 (max)	
Nonrecoverable read errors	1 per 10 <sup>14</sup> bits read	1 per 10 <sup>14</sup> bits read	
Annualized Failure Rate (AFR)	0.34%		
Warranty	To determine the warranty access the following web p www.seagate.com/support From this page, click on the asked to provide the drive	5 years on distribution units. To determine the warranty for a specific drive, use a web browser to access the following web page: www.seagate.com/support/service/ From this page, click on the "Verify Your Warranty" link. You will be asked to provide the drive serial number, model number (or part number) and country of purchase. The system will display the warranty information for your drive.	
Contact start-stop cycles (25°C, 50% rel. humidity)	50,000	50,000	
Supports Hotplug operation per SATA II specification	Yes	Yes	

<sup>\*</sup>One Gbyte equals one billion bytes when referring to hard drive capacity. Accessible capacity may vary depending on operating environment and formatting.

<sup>\*\*</sup>During periods of drive idle, some offline activity may occur according to the S.M.A.R.T. specification, which may increase acoustic and power to operational levels.

Table 7: Drive specifications summary for 120 Gbyte models

Drive specification	ST3120813AS	ST3120213AS	
Formatted Gbytes (512 bytes/sector)*	120		
Guaranteed sectors	234,441,648		
Bytes per sector	512		
Default sectors per track	63		
Default read/write heads	16		
Default cylinders	16,383		
Recording density, KBPI (kbits/in max)	840.0		
Track density, KTPI (ktracks/in avg.)	141.5		
Areal density, (Gbits/in <sup>2</sup> avg)	119.0		
Spindle speed (RPM)	7,200		
Internal data transfer rate (Mbits/sec max)	867.2		
Sustained data transfer rate OD (Mbytes/sec max)	83		
I/O data-transfer rate (Mbytes/sec max)	300		
ATA data-transfer modes supported	PIO modes 0–4 Multiword DMA modes 0–2 Ultra DMA modes 0–6		
Cache buffer	8 Mbytes	2 Mbytes	
Height (mm max)	26.1 mm (1.028 inches)		
Width (mm max)	101.6 mm (4.000 inches) +/- 0.01	0 inches	
Length (mm max)	146.99 mm (5.787 inches)		
Weight (max)	580 grams (1.28 lb.)		
Average latency (msec)	4.16		
Power-on to ready (sec max)	<10.0 sec		
Standby to ready (sec max)	<10.0 sec		
Track-to-track seek time (msec typical)	<0.8 (read), <1.0 (write)		
Average seek, read (msec typical)	<8.0 (ST3120813AS & ST3120213AS models) <9.9 ( & models)		
Average seek, write (msec typical)	<9.0 (ST3120813AS & ST312021 <10.9 ( & models)	3AS models)	
Startup current (typical) 12V (peak)	2.8 amps		
Voltage tolerance (including noise)	5V ± 5% 12V ± 10%		
Ambient temperature	0° to 60°C (operating) -40° to 70°C (nonoperating)		
Temperature gradient (°C per hour max)	20°C (operating) 30°C (nonoperating)		
Relative humidity	5% to 90% (operating) 5% to 95% (nonoperating)		
Relative humidity gradient	30% per hour max		
Wet bulb temperature (°C max)	37.7 (operating) 40.0 (nonoperating)		
Altitude, operating	-60.96 m to 3,048 m (-200 ft. to 10,000+ ft.)		
Altitude, nonoperating (below mean sea level, max)	-60.96 m to 12,192 m (-200 ft. to 40,000+ ft.)		
Operational Shock (Gs max at 2 msec)	63		
Non-Operational Shock (Gs max at 2 msec)	350 Gs	350 Gs	

Drive specification	ST3120813AS	ST3120213AS	
Vibration, operating	5–22 Hz: 0.25 Gs, Limited 22–350 Hz: 0.5 Gs 350–500 Hz:: 0.25 Gs	displacement	
Vibration, nonoperating	5–22 Hz: 0.25 Gs, Limited 22–350 Hz: 5.0 Gs 350–500 Hz:: 1.0 Gs	displacement	
Drive acoustics, sound power (bels)			
Idle**	2.5 (typical) 2.7 (max)	2.5 (typical) 2.7 (max)	
Performance seek	3.3 (typical) 3.5 (max)	3.3 (typical) 3.5 (max)	
Nonrecoverable read errors	1 per 10 <sup>14</sup> bits read	1 per 10 <sup>14</sup> bits read	
Annualized Failure Rate (AFR)	0.34%		
Warranty	To determine the warranty access the following web p www.seagate.com/support. From this page, click on the to provide the drive serial n	5 years on distribution units. To determine the warranty for a specific drive, use a web browser to access the following web page: www.seagate.com/support/service/ From this page, click on the "Verify Your Warranty" link. You will be asked to provide the drive serial number, model number (or part number) and country of purchase. The system will display the warranty information for your drive.	
Contact start-stop cycles (25°C, 50% rel. humidity)	50,000	50,000	
Supports Hotplug operation per SATA II specification	Yes		

<sup>\*</sup>One Gbyte equals one billion bytes when referring to hard drive capacity. Accessible capacity may vary depending on operating environment and formatting.

<sup>\*\*</sup>During periods of drive idle, some offline activity may occur according to the S.M.A.R.T. specification, which may increase acoustic and power to operational levels.

Table 8: Drive specifications summary for 80 and 40 Gbyte models

Drive specification	ST3808110AS	ST3802110AS	ST3402111AS
Formatted Gbytes (512 bytes/sector)*	80		40
Guaranteed sectors	156,301,488		78,165,360
Bytes per sector	512		·
Default sectors per track	63		
Default read/write heads	16		
Default cylinders	16,383		
Recording density, KBPI (kbits/in max)	840.0		611.5
Track density, KTPI (ktracks/in avg.)	141.5		103.9
Areal density, (Gbits/in <sup>2</sup> avg)	119.0		63.53
Spindle speed (RPM)	7,200		·
Internal data transfer rate (Mbits/sec max)	867.2		
Sustained data transfer rate OD (Mbytes/sec max)	83		69.375
I/O data-transfer rate (Mbytes/sec max)	300		·
ATA data-transfer modes supported	PIO modes 0–4 Multiword DMA modes 0 Ultra DMA modes 0–6	)–2	
Cache buffer	8 Mbytes	2 Mbytes	
Height (mm max)	26.1 mm (1.028 inches)		
Width (mm max)	101.6 mm (4.000 inches) +/- 0.010 inches		
Length (mm max)	146.99 mm (5.787 inches)		
Weight (max)	580 grams (1.28 lb.)		
Average latency (msec)	4.16		
Power-on to ready (sec max)	<10.0 sec		
Standby to ready (sec max)	<10.0 sec		
Track-to-track seek time (msec typical)	<0.8 (read), <1.0 (write)	)	
Average seek, read (msec typical)	<9.5	<9.5	<14.0
Average seek, write (msec typical)	<10.5	<10.5	<16.0
Startup current (typical) 12V (peak)	2.8 amps		<u>.                                      </u>
Voltage tolerance (including noise)	5V ± 5% 12V ± 10%		
Ambient temperature	0° to 60°C (operating) -40° to 70°C (nonoperating)	ting)	
Temperature gradient (°C per hour max)	20°C (operating) 30°C (nonoperating)		
Relative humidity	5% to 90% (operating) 5% to 95% (nonoperatin	g)	
Relative humidity gradient	30% per hour max		
Wet bulb temperature (°C max)	37.7 (operating) 40.0 (nonoperating)		
Altitude, operating	-60.96 m to 3,048 m (-200 ft. to 10,000+ ft.)		
Altitude, nonoperating (below mean sea level, max)	-60.96 m to 12,192 m (-200 ft. to 40,000+ ft.)		
Operational Shock (Gs max at 2 msec)	63		
Non-Operational Shock (Gs max at 2 msec)	350 Gs		
Vibration, operating	5–22 Hz: 0.25 Gs, Limite 22–350 Hz: 0.5 Gs 350–500 Hz:: 0.25 Gs	ed displacement	

Drive specification	ST3808110AS	ST3802110AS	ST3402111AS	
Vibration, nonoperating	5–22 Hz: 0.25 Gs, L 22–350 Hz: 5.0 Gs 350–500 Hz:: 1.0 G	imited displacement s		
Drive acoustics, sound power (bels)				
Idle**	2.5 (typical) 2.7 (max)	2.5 (typical) 2.7 (max)	2.5 (typical) 2.7 (max)	
Performance seek	3.0 (typical) 3.2 (max)	3.0 (typical) 3.2 (max)	N/A N/A	
Nonrecoverable read errors	1 per 10 <sup>14</sup> bits read	1 per 10 <sup>14</sup> bits read		
Annualized Failure Rate (AFR)	0.34%	0.34%		
Warranty	To determine the wa the following web pa www.seagate.com/s From this page, clic provide the drive se	5 years on distribution units. To determine the warranty for a specific drive, use a web browser to access the following web page: www.seagate.com/support/service/ From this page, click on the "Verify Your Warranty" link. You will be asked to provide the drive serial number, model number (or part number) and country of purchase. The system will display the warranty information for your drive.		
Contact start-stop cycles (25°C, 50% rel. humidity)	50,000	50,000		
Supports Hotplug operation per SATA II specification	Yes			

<sup>\*</sup>One Gbyte equals one billion bytes when referring to hard drive capacity. Accessible capacity may vary depending on operating environment and formatting.

<sup>\*\*</sup>During periods of drive idle, some offline activity may occur according to the S.M.A.R.T. specification, which may increase acoustic and power to operational levels.

## 2.2 Formatted capacity

Model	Formatted capacity*	Guaranteed sectors	Bytes per sector
ST3500641AS	500 Gbytes	976,773,168	512
ST3500841AS	500 Gbytes	976,773,168	512
ST3400633AS	400 Gbytes	781,422,768	512
ST3400833AS	400 Gbytes	781,422,768	512
ST3320633AS	320 Gbytes	625,142,448	512
ST3320833AS	320 Gbytes	625,142,448	512
ST3300622AS	300 Gbytes	586,072,368	512
ST3300822AS	300 Gbytes	586,072,368	512
ST3250624AS	250 Gbytes	488,397,168	512
ST3250824AS	250 Gbytes	488,397,168	512
ST3200827AS	200 Gbytes	390,721,968	512
ST3160812AS	160 Gbytes	312,581,808	512
ST3160212AS	160 Gbytes	312,581,808	512
ST3120813AS	120 Gbytes	234,441,648	512
ST3120213AS	120 Gbytes	234,441,648	512
ST3808110AS	80 Gbytes	156,301,488	512
ST3802110AS	80 Gbytes	156,301,488	512
ST3402111AS	40 Gbytes	78,165,360	512

<sup>\*</sup>One Gbyte equals one billion bytes when referring to hard drive capacity. Accessible capacity may vary depending on operating environment and formatting.

#### 2.2.1 LBA mode

When addressing these drives in LBA mode, all blocks (sectors) are consecutively numbered from 0 to n–1, where n is the number of guaranteed sectors as defined above.

See Section 4.3.1, "Identify Device command" (words 60-61 and 100-103) for additional information about 48-bit addressing support of drives with capacities over 137 Gbytes.

## 2.3 Default logical geometry

Cylinders	Read/write heads	Sectors per track
16,383	16	63

## LBA mode

When addressing these drives in LBA mode, all blocks (sectors) are consecutively numbered from 0 to n–1, where n is the number of guaranteed sectors as defined above.

# 2.4 Recording and interface technology

Interface	Serial ATA (SATA)
Recording method	16/17 EPRML
Recording density KBPI (kbits/inch max)	790.1 (500, 400, 320, 300, 250, 200GB models) 840.0 (160, 120 and 80GB models) 611.5 (40GB model)
Track density KTPI (ktracks/inch avg)	124.5 (500, 400, 320, 300, 250, 200GB models) 141.5 (160, 120 and 80GB models) 103.9 (40GB model)
Areal density (Gbits/inch <sup>2</sup> avg)	97.96 (500, 400, 320, 300, 250, 200GB models) 119.0 (160, 120 and 80GB models) 63.53 (40GB model)
Spindle speed (RPM) (± 0.2%)	7,200
Internal data-transfer rate (Mbits/sec max)	815.2 (400 and 500GB models) 867.2 (all other models)
Sustained data transfer rate OD (Mbytes/sec max)	65 (400 and 500GB models) 76.6 (320, 300, 250 and 200GB models) 83 (160, 120 and 80GB models) 69.375 (40GB model)
I/O data-transfer rate (Mbytes/sec max)	300
Interleave	1:1
Cache buffer  ST3500641AS ST3400633AS ST3320633AS ST3300622AS ST3250624AS	16 Mbytes (16,384 kbytes)
ST3500841AS ST3400833AS ST3320833AS ST3300822AS ST3250824AS ST3200827AS ST3160812AS ST3120813AS ST3808110AS	8 Mbytes (8,192 kbytes)
ST3160212AS ST3120213AS ST3802110AS ST3402111AS	2 Mbytes (2,048 kbytes)

## 2.5 Physical characteristics

Maximum height	
(mm)	
(inches)	19.99
	0.787
Maximum height	
(mm)	26.1
(inches)	1.028
Maximum width	
(mm)	101.6
(inches)	4.000 +/- 0.010
Maximum length	
(mm)	146.99
(inches)	5.787
Max weight	
40, 60, 80, 120, 200, and 250 GB models	580 grams (1.28 lbs)
320 and 300GB models	655 grams (1.44 lbs)
400 and 500GB models	710 grams (1.57 lbs)

#### 2.6 Seek time

Seek measurements are taken with nominal power at 25°C ambient temperature. All times are measured using drive diagnostics. The specifications in the table below are defined as follows:

- Track-to-track seek time is an average of all possible single-track seeks in both directions.
- Average seek time is a true statistical random average of at least 5,000 measurements of seeks between random tracks, less overhead.

*Typical seek times (msec)	Models	Read	Write
Track-to-track		<0.8	<1.0
	All 400 and 500GB	<8.2	<9.0
Average	All 320, 300, 250, 200, 160 and 120GB	<8.0	<9.0
	All 80GB	<9.5	<10.5
Average latency:	All	4.16	4.16

<sup>\*</sup>Measured in performance mode unless otherwise noted.

**Note.** These drives are designed to consistently meet the seek times represented in this manual. Physical seeks, regardless of mode (such as track-to-track and average), are expected to meet the noted values. However, due to the manner in which these drives are formatted, benchmark tests that include command overhead or measure logical seeks may produce results that vary from these specifications.

## 2.7 Start/stop times

	400 and 500GB models	320, 300, 250, 200, 160, 120, 80 and 40GB models
Power-on to Ready (sec)	13 (max)	11 (max)
Standby to Ready (sec)	13 (max)	11 (max)
Ready to spindle stop (sec)	14 (max)	12 (max)

## 2.8 Power specifications

The drive receives DC power (+5V or +12V) through a native SATA power connector. See Figure 4 on page 34.

## 2.8.1 Power consumption

Power requirements for the drives are listed in the table on page 9. Typical power measurements are based on an average of drives tested, under nominal conditions, using 5.0V and 12.0V input voltage at 25°C ambient temperature.

## Spinup power

Spinup power is measured from the time of power-on to the time that the drive spindle reaches operating speed.

#### · Seek mode

During seek mode, the read/write actuator arm moves toward a specific position on the disc surface and does not execute a read or write operation. Servo electronics are active. Seek mode power represents the worst-case power consumption, using only random seeks with read or write latency time. This mode is not typical and is provided for worst-case information.

## Read/write power and current

Read/write power is measured with the heads on track, based on a 16-sector write followed by a 32-msec delay, then a 16-sector read followed by a 32-msec delay.

#### Operating power and current

Operating power is measured using 40 percent random seeks, 40 percent read/write mode (1 write for each 10 reads) and 20 percent drive idle mode.

#### • Idle mode power

Idle mode power is measured with the drive up to speed, with servo electronics active and with the heads in a random track location.

#### Standby mode

During Standby mode, the drive accepts commands, but the drive is not spinning, and the servo and read/write electronics are in power-down mode.

Table 9: DC power requirements (for all 500GB and 400GB models))

Power dissipation (watts)	Avg (watts, 25° C)	Avg 5V typ amps	Avg 12V typ amps
Spinup	_	_	2.90 (peak)
Idle*	9.30	0.608	0.522
Idle* (with offline activity)	10.40	0.660	0.592
Operating (40% r/w, 40% seek, 20% inop.)	13.00	0.978	0.676
Seeking (random, 20% idle)	12.60	0.795	0.719
Standby	1.25	0.228	0.009
Sleep	1.25	0.209	0.017

Table 10: DC power requirements (for all 320GB, 300GB, 250GB and 200GB models)

Power dissipation (watts)	Avg (watts, 25° C)	Avg 5V typ amps	Avg 12V typ amps
Spinup	_	_	2.80 (peak)
Idle*	7.75	0.512	0.432
Idle* (with offline activity)	8.93	0.749	0.432
Operating (40% r/w, 40% seek, 20% inop.)	9.82	0.623	0.559
Seeking (random, 20% idle)	11.35	0.497	0.738
Standby	1.24	0.221	0.011
Sleep	1.24	0.220	0.011

Table 11: DC power requirements (for all 160GB and 120GB models)

Power dissipation (watts)	Avg (watts, 25° C)	Avg 5V typ amps	Avg 12V typ amps
Spinup	_	_	2.80 (peak)
ldle*	7.20	0.590	0.354
Idle* (with offline activity)	9.10	0.880	0.391
Operating (40% r/w, 40% seek, 20% inop.)	12.80	0.920	0.682
Seeking (random, 20% idle)	12.40	0.690	0.745
Standby	1.30	0.234	0.011
Sleep	1.30	0.234	0.011

Table 12: DC power requirements (for all 80GB and 40GB models)

Power dissipation (watts)	Avg (watts, 25° C)	Avg 5V typ amps	Avg 12V typ amps
Spinup	_	_	2.80 (peak)
Idle*	7.00	0.490	0.379
Idle* (with offline activity)	8.90	0.873	0.378
Operating (40% r/w, 40% seek, 20% inop.)	12.60	0.897	0.676
Seeking (random, 20% idle)	12.20	0.627	0.755
Standby	1.30	0.230	0.013
Sleep	1.30	0.230	0.013

<sup>\*</sup>During periods of drive idle, some offline activity may occur according to the S.M.A.R.T. specification, which may increase acoustic and power to operational levels.

## 2.8.1.1 Typical current profiles

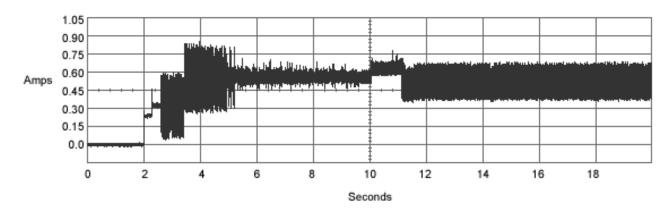


Figure 1. Typical 5V startup and operation current profile

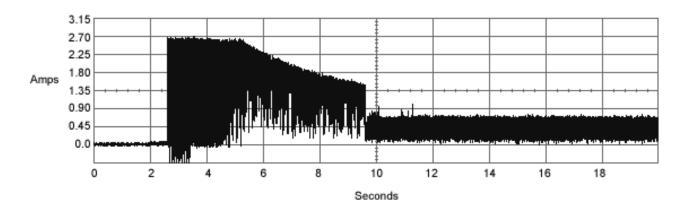


Figure 2. Typical 12V startup and operation current profile

#### 2.8.2 Conducted noise

Input noise ripple is measured at the host system power supply across an equivalent 80-ohm resistive load on the +12 volt line or an equivalent 15-ohm resistive load on the +5 volt line.

- Using 12-volt power, the drive is expected to operate with a maximum of 120 mV peak-to-peak square-wave injected noise at up to 10 MHz.
- Using 5-volt power, the drive is expected to operate with a maximum of 100 mV peak-to-peak square-wave injected noise at up to 10 MHz.

**Note.** Equivalent resistance is calculated by dividing the nominal voltage by the typical RMS read/write current.

## 2.8.3 Voltage tolerance

Voltage tolerance (including noise):

5V ± 5% 12V ± 10%

## 2.8.4 Power-management modes

The drive provides programmable power management to provide greater energy efficiency. In most systems, you can control power management through the system setup program. The drive features the following power-management modes:

Power modes	Heads	Spindle	Buffer
Active	Tracking	Rotating	Enabled
Idle	Tracking	Rotating	Enabled
Standby	Parked	Stopped	Enabled
Sleep	Parked	Stopped	Disabled

#### Active mode

The drive is in Active mode during the read/write and seek operations.

#### Idle mode

The buffer remains enabled, and the drive accepts all commands and returns to Active mode any time disc access is necessary.

#### Standby mode

The drive enters Standby mode when the host sends a Standby Immediate command. If the host has set the standby timer, the drive can also enter Standby mode automatically after the drive has been inactive for a specifiable length of time. The standby timer delay is established using a Standby or Idle command. In Standby mode, the drive buffer is enabled, the heads are parked and the spindle is at rest. The drive accepts all commands and returns to Active mode any time disc access is necessary.

#### Sleep mode

The drive enters Sleep mode after receiving a Sleep command from the host. In Sleep mode, the drive buffer is disabled, the heads are parked and the spindle is at rest. The drive leaves Sleep mode after it receives a Hard Reset or Soft Reset from the host. After receiving a reset, the drive exits Sleep mode and enters Standby mode with all current translation parameters intact.

#### Idle and Standby timers

Each time the drive performs an Active function (read, write or seek), the standby timer is reinitialized and begins counting down from its specified delay times to zero. If the standby timer reaches zero before any drive activity is required, the drive makes a transition to Standby mode. In both Idle and Standby mode, the drive accepts all commands and returns to Active mode when disc access is necessary.

## 2.9 Environmental specifications

## 2.9.1 Ambient temperature

Ambient temperature is defined as the temperature of the environment immediately surrounding the drive. Actual drive case temperature should not exceed 69°C (156°F) within the operating ambient conditions.

Above 1,000 feet (305 meters), the maximum temperature is derated linearly to 112°F (44°C) at 10,000 feet (3,048 meters).

Operating:	0° to 60°C (32° to 140°F)
Nonoperating:	-40° to 70°C (-40° to 158°F)

## 2.9.2 Temperature gradient

Operating:	20°C per hour (68°F per hour max), without condensation
Nonoperating:	30°C per hour (86°F per hour max)

## 2.9.3 Humidity

## 2.9.3.1 Relative humidity

Operating:	5% to 90% noncondensing (30% per hour max)
Nonoperating:	5% to 95% noncondensing (30% per hour max)

#### 2.9.3.2 Wet bulb temperature

Operating:	37.7°C (99.9°F max)
Nonoperating:	40.0°C (104°F max)

#### 2.9.4 Altitude

Operating:	-60.96 m to 3,048 m (-200 ft. to 10,000+ ft.)
Nonoperating:	-60.96 m to 12,192 m (-200 ft. to 40,000+ ft.)

## 2.9.5 Shock

All shock specifications assume that the drive is mounted securely with the input shock applied at the drive mounting screws. Shock may be applied in the X, Y or Z axis.

## 2.9.5.1 Operating shock

These drives comply with the performance levels specified in this document when subjected to a maximum operating shock of 63 Gs based on half-sine shock pulses of 2 msec. Shocks should not be repeated more than two times per second.

## 2.9.5.2 Nonoperating shock

The nonoperating shock level that the drive can experience without incurring physical damage or degradation in performance when subsequently put into operation is 350 Gs (except 500GB is 300 Gs) based on a nonrepetitive half-sine shock pulse of 2 msec duration.

#### 2.9.6 Vibration

All vibration specifications assume that the drive is mounted securely with the input vibration applied at the drive mounting screws. Vibration may be applied in the X, Y or Z axis.

## 2.9.6.1 Operating vibration

The maximum vibration levels that the drive may experience while meeting the performance standards specified in this document are specified below.

5–22 Hz	0.25 Gs (Limited displacement)
23–350 Hz	0.50 Gs
350–500 Hz	0.25 Gs

## 2.9.6.2 Nonoperating vibration

The maximum nonoperating vibration levels that the drive may experience without incurring physical damage or degradation in performance when subsequently put into operation are specified below.

5–22 Hz	0.25 Gs (limited displacement)
23–350 Hz	5.0 Gs
350–500 Hz	1.0 Gs

#### 2.10 Acoustics

Drive acoustics are measured as overall A-weighted acoustic sound power levels (no pure tones). All measurements are consistent with ISO document 7779. Sound power measurements are taken under essentially free-field conditions over a reflecting plane. For all tests, the drive is oriented with the cover facing upward.

**Note.** For seek mode tests, the drive is placed in seek mode only. The number of seeks per second is defined by the following equation:

(Number of seeks per second = 0.4 / (average latency + average access time)

Table 13: Fluid Dynamic Bearing (FDB) motor acoustics

Acoustic mode		
	Idle*	Performance seek
ST3402111AS	2.5 bels (typ) 2.7 bels (max)	N/A N/A
ST3802110AS, ST3808110AS	2.5 bels (typ) 2.7 bels (max)	3.0 bels (typ) 3.2 bels (max)
ST3120213AS, ST3120813AS, ST3160212AS, ST3160812AS	2.5 bels (typ) 2.7 bels (max)	3.3 bels (typ) 3.5 bels (max)
ST3200827AS, ST3250824AS, ST3250624AS, ST3300622AS, ST3300822AS, ST3320833AS, ST3320633AS	2.7 bels (typ) 2.9 bels (max)	3.4 bels (typ) 3.6 bels (max)
ST3500641AS, ST3500841AS, ST3400633AS, ST3400833AS	2.8 bels (typ) 3.0 bels (max)	3.7 bels (typ) 3.9 bels (max)

<sup>\*</sup>During periods of drive idle, some offline activity may occur according to the S.M.A.R.T. specification, which may increase acoustic and power to operational levels.

## 2.11 Electromagnetic immunity

When properly installed in a representative host system, the drive operates without errors or degradation in performance when subjected to the radio frequency (RF) environments defined in the following table:

Table 14: Radio frequency environments

Test	Description	Performance level	Reference standard
Electrostatic discharge	Contact, HCP, VCP: ± 4 kV; Air: ± 8 kV	В	EN 61000-4-2: 95
Radiated RF immunity	80 to 1,000 MHz, 3 V/m, 80% AM with 1 kHz sine 900 MHz, 3 V/m, 50% pulse modulation @ 200 Hz	A	EN 61000-4-3: 96 ENV 50204: 95
Electrical fast transient	± 1 kV on AC mains, ± 0.5 kV on external I/O	В	EN 61000-4-4: 95
Surge immunity	± 1 kV differential, ± 2 kV common, AC mains	В	EN 61000-4-5: 95
Conducted RF immunity	150 kHz to 80 MHz, 3 Vrms, 80% AM with 1 kHz sine	А	EN 61000-4-6: 97
Voltage dips, interrupts	0% open, 5 seconds 0% short, 5 seconds 40%, 0.10 seconds 70%, 0.01 seconds	ССССВ	EN 61000-4-11: 94

## 2.12 Reliability

Nonrecoverable read errors	1 per 10 <sup>14</sup> bits read, max
Annualized Failure Rate (AFR)	0.34% (nominal power, 25°C ambient temperature)
Contact start-stop cycles	50,000 cycles (at nominal voltage and temperature, with 60 cycles per hour and a 50% duty cycle)
Warranty	5 years on distribution units.  To determine the warranty for a specific drive, use a web browser to access the following web page:  www.seagate.com/support/service/  From this page, click on the "Verify Your Warranty" link. You will be asked to provide the drive serial number, model number (or part number) and country of purchase. The system will display the warranty information for your drive.
Preventive maintenance	None required.

## 2.13 Agency certification

#### 2.13.1 Safety certification

The drives are recognized in accordance with UL 1950 and CSA C22.2 (950) and meet all applicable sections of IEC950 and EN 60950 as tested by TUV North America.

### 2.13.2 Electromagnetic compatibility

Hard drives that display the CE mark comply with the European Union (EU) requirements specified in the Electromagnetic Compatibility Directive (89/336/EEC). Testing is performed to the levels specified by the product standards for Information Technology Equipment (ITE). Emission levels are defined by EN 55022, Class B and the immunity levels are defined by EN 55024.

Seagate uses an independent laboratory to confirm compliance with the EC directives specified in the previous paragraph. Drives are tested in representative end-user systems. Although CE-marked Seagate drives comply with the directives when used in the test systems, we cannot guarantee that all systems will comply with the directives. The drive is designed for operation inside a properly designed enclosure, with properly shielded I/O cable (if necessary) and terminators on all unused I/O ports. Computer manufacturers and system integrators should confirm EMC compliance and provide CE marking for their products.

#### Korean RRL

If these drives have the Korea Ministry of Information and Communication (MIC) logo, they comply with paragraph 1 of Article 11 of the Electromagnetic Compatibility control Regulation and meet the Electromagnetic Compatibility (EMC) Framework requirements of the Radio Research Laboratory (RRL) Ministry of Information and Communication Republic of Korea.

These drives have been tested and comply with the Electromagnetic Interference/Electromagnetic Susceptibility (EMI/EMS) for Class B products. Drives are tested in a representative, end-user system by a Korean-recognized lab.

- EUT name (model numbers): See table below.
- · Certificate numbers:

Model	Certificate Number
ST3500841AS, ST3500641AS,ST3400833AS,ST3400633AS, ST3320833AS, ST3320633AS, ST3300822AS, ST3300622AS, ST3250824AS, ST3250624AS, ST3200827AS, ST3160812AS, ST3160212AS, ST3120813AS, ST3120213AS, ST3808110AS, ST3802110AS, ST3402111AS	E-H011-05-3453 (B)

- Trade name or applicant: Seagate Technology
- Manufacturing date: September 2005
- Manufacturer/nationality: Singapore and China

#### Australian C-Tick (N176)

If these models have the C-Tick marking, they comply with the Australia/New Zealand Standard AS/NZS3548 1995 and meet the Electromagnetic Compatibility (EMC) Framework requirements of the Australian Communication Authority (ACA).

#### 2.13.3 FCC verification

These drives are intended to be contained solely within a personal computer or similar enclosure (not attached as an external device). As such, each drive is considered to be a subassembly even when it is individually marketed to the customer. As a subassembly, no Federal Communications Commission verification or certification of the device is required.

Seagate Technology LLC has tested this device in enclosures as described above to ensure that the total assembly (enclosure, disc drive, motherboard, power supply, etc.) does comply with the limits for a Class B computing device, pursuant to Subpart J, Part 15 of the FCC rules. Operation with noncertified assemblies is likely to result in interference to radio and television reception.

**Radio and television interference.** This equipment generates and uses radio frequency energy and if not installed and used in strict accordance with the manufacturer's instructions, may cause interference to radio and television reception.

This equipment is designed to provide reasonable protection against such interference in a residential installation. However, there is no guarantee that interference will not occur in a particular installation. If this equipment does cause interference to radio or television, which can be determined by turning the equipment on and off, you are encouraged to try one or more of the following corrective measures:

- · Reorient the receiving antenna.
- Move the device to one side or the other of the radio or TV.
- Move the device farther away from the radio or TV.
- Plug the computer into a different outlet so that the receiver and computer are on different branch outlets.

If necessary, you should consult your dealer or an experienced radio/television technician for additional suggestions. You may find helpful the following booklet prepared by the Federal Communications Commission: *How to Identify and Resolve Radio-Television Interference Problems.* This booklet is available from the Superintendent of Documents, U.S. Government Printing Office, Washington, DC 20402. Refer to publication number 004-000-00345-4.

## 2.14 Environmental protection

Seagate designs its products to meet environmental protection requirements worldwide, including regulations restricting certain chemical substances.

### 2.14.1 European Union Restriction of Hazardous Substances (RoHS)

The European Union Restriction of Hazardous Substances (RoHS) Directive restricts the presence of chemical substances, including Lead (Pb), in electronic products effective July 2006. Although amendments to the Euro-pean Union's Restriction of Hazardous Substances (RoHS) Directive have not been finalized, to the best of our knowledge the disc drives documented in this publication will comply with the final RoHS Directive require-ments.

A number of parts and materials in Seagate products are procured from external suppliers. We rely on the rep-resentations of our suppliers regarding the presence of RoHS substances in these parts and materials. Our supplier contracts require compliance with our chemical substance restrictions, and our suppliers document their compliance with our requirements by providing material content declarations for all parts and materials for the disc drives documented in this publication. Current supplier declarations include disclosure of the inclusion of any RoHS-regulated substance in such parts or materials.

Seagate also has internal systems in place to ensure ongoing compliance with the RoHS Directive and all laws and regulations which restrict chemical content in electronic products. These systems include standard operat-ing procedures that ensure that restricted substances are not utilized in our manufacturing operations, labora-tory analytical validation testing, and an internal auditing process to ensure that all standard operating procedures are complied with.

### 2.15 Corrosive environment

Seagate electronic drive components pass accelerated corrosion testing equivalent to 10 years exposure to light industrial environments containing sulfurous gases, chlorine and nitric oxide, classes G and H per ASTM B845. However, this accelerated testing cannot duplicate every potential application environment. Users should use caution exposing any electronic components to uncontrolled chemical pollutants and corrosive chemicals as electronic drive component reliability can be affected by the installation environment. The silver, copper, nickel and gold films used in Seagate products are especially sensitive to the presence of sulfide, chloride, and nitrate contaminants. Sulfur is found to be the most damaging. In addition, electronic components should never be exposed to condensing water on the surface of the printed circuit board assembly (PCBA) or exposed to an ambient relative humidity greater than 95%. Materials used in cabinet fabrication, such as vulcanized rubber, that can outgas corrosive compounds should be minimized or eliminated. The useful life of any electronic equipment may be extended by replacing materials near circuitry with sulfide-free alternatives.

# 3.0 Configuring and mounting the drive

This section contains the specifications and instructions for configuring and mounting the drive.

## 3.1 Handling and static-discharge precautions

After unpacking, and before installation, the drive may be exposed to potential handling and electrostatic discharge (ESD) hazards. Observe the following standard handling and static-discharge precautions:

#### Caution:

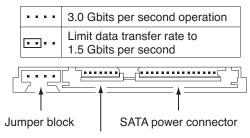
- Before handling the drive, put on a grounded wrist strap, or ground yourself frequently by touching the metal
  chassis of a computer that is plugged into a grounded outlet. Wear a grounded wrist strap throughout the entire
  installation procedure.
- Handle the drive by its edges or frame only.
- The drive is extremely fragile—handle it with care. Do not press down on the drive top cover.
- Always rest the drive on a padded, antistatic surface until you mount it in the computer.
- Do not touch the connector pins or the printed circuit board.
- Do not remove the factory-installed labels from the drive or cover them with additional labels. Removal voids the warranty. Some factory-installed labels contain information needed to service the drive. Other labels are used to seal out dirt and contamination.

## 3.2 Configuring the drive

Each drive on the Serial ATA interface connects point-to-point with the Serial ATA host adapter. There is no master/slave relationship because each drive is considered a master in a point-to-point relationship. If two drives are attached on one Serial ATA host adapter, the host operating system views the two devices as if they were both "masters" on two separate ports. Both drives behave as if they are Device 0 (master) devices.

Serial ATA drives are designed for easy installation. It is usually not necessary to set any jumpers on the drive for proper operation; however, if you connect the drive and receive a "drive not detected" error, your SATA-equipped motherboard or host adapter may use a chipset that does not support SATA speed autonegotiation. If you have a motherboard or host adapter that does not support autonegotiation:

- Configure the jumper block with a jumper as shown in Figure 3 below to limit the data transfer rate to 1.5 Gbits
  per second (and leave the drive connected to the SATA-equipped motherboard or host adapter that doesn't
  support autonegotiation) or
- Install a SATA host adapter that supports autonegotiation, set the drive jumper block to "3 Gbits per second operation" (see Figure 3 below), and connect the drive to that adapter. This option has the benefit of not limiting the drive to a 1.5 Gbits/sec transfer rate.



SATA interface connector

Figure 3. Serial ATA connectors and jumper options

#### 3.3 Serial ATA cables and connectors

The Serial ATA interface cable consists of four conductors in two differential pairs, plus three ground connections. The cable size may be 30 to 26 AWG with a maximum length of one meter (39.37 inches). See Table 15 for connector pin definitions. Either end of the SATA signal cable can be attached to the drive or host.

For direct backplane connection, the drive connectors are inserted directly into the host receptacle. The drive and the host receptacle incorporate features that enable the direct connection to be hot pluggable and blind mateable.

For installations which require cables, you can connect the drive as illustrated in Figure 4.

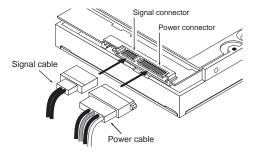


Figure 4. Attaching SATA cabling

Each cable is keyed to ensure correct orientation. Barracuda 7200.9 Serial ATA drives support latching SATA connectors.

## 3.4 Drive mounting

You can mount the drive in any orientation using four screws in the side-mounting holes or four screws in the bottom-mounting holes. See Figure 5 on page 35 for drive mounting dimensions. Follow these important mounting precautions when mounting the drive:

- Allow a minimum clearance of 0.030 inches (0.76 mm) around the entire perimeter of the drive for cooling.
- Use only 6-32 UNC mounting screws.
- The screws should be inserted no more than 0.150 inch (3.81 mm) into the bottom or side mounting holes.
- Do not overtighten the mounting screws (maximum torque: 6 inch-lb).

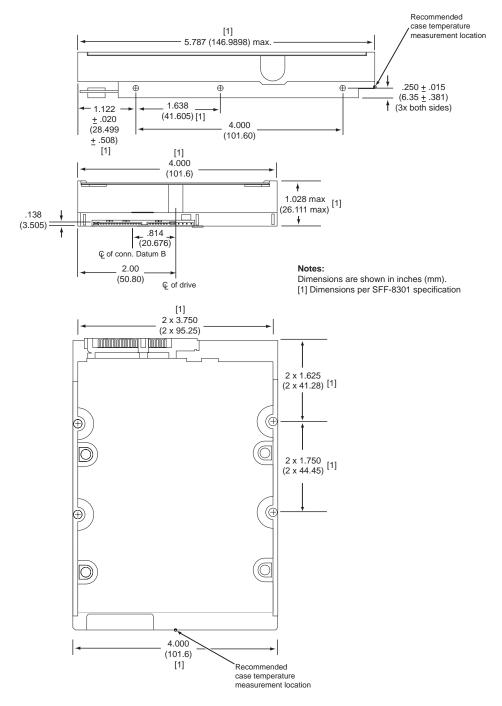


Figure 5. Mounting dimensions—top, side and end view

# 4.0 Serial ATA (SATA) interface

These drives use the industry-standard Serial ATA interface that supports FIS data transfers. It supports ATA programmed input/output (PIO) modes 0–4; multiword DMA modes 0–2, and Ultra DMA modes 0–6.

For detailed information about the Serial ATA interface, refer to the "Serial ATA: High Speed Serialized AT Attachment" specification.

## 4.1 Hot-Plug compatibility

Barracuda 7200.9 Serial ATA drives incorporate connectors which enable you to hot plug these drives in accordance with the Serial ATA II: Extension to Serial ATA 1.0a specification. This specification can be downloaded from www.serialata.org.

## 4.2 Serial ATA device plug connector pin definitions

Table 15 summarizes the signals on the Serial ATA interface and power connectors..

Table 15: Serial ATA connector pin definitions

Segment	Pin	Function	Definition	
	S1	Ground	2nd mate	
	S2	A+	Differential signal pair A from Phy	
	S3	A-		
	S4	Ground	2nd mate	
	S5	B-	Differential signal pair B from Phy	
	S6	B+		
Signal	S7	Ground	2nd mate	
Key and spacing separate signal and power segments				
	P1	V <sub>33</sub>	3.3V power	
	P2	V <sub>33</sub>	3.3V power	
	P3	V <sub>33</sub>	3.3V power, pre-charge, 2nd mate	
	P4	Ground	1st mate	
	P5	Ground	2nd mate	
	P6	Ground	2nd mate	
	P7	V <sub>5</sub>	5V power, pre-charge, 2nd mate	
Power	P8	V <sub>5</sub>	5V power	
	P9	V <sub>5</sub>	5V power	
	P10	Ground	2nd mate	
	P11	Ground or LED signal	If grounded, drive does not use deferred spin	
	P12	Ground	1st mate.	
	P13	V <sub>12</sub>	12V power, pre-charge, 2nd mate	
	P14	V <sub>12</sub>	12V power	
	P15	V <sub>12</sub>	12V power	

#### Notes:

- 1. All pins are in a single row, with a 1.27 mm (0.050") pitch.
- 2. The comments on the mating sequence apply to the case of backplane blindmate connector only. In this case, the mating sequences are:
  - the ground pins P4 and P12.
  - the pre-charge power pins and the other ground pins.
  - · the signal pins and the rest of the power pins.
- 3. There are three power pins for each voltage. One pin from each voltage is used for pre-charge when installed in a blind-mate backplane configuration.
- 4. All used voltage pins  $(V_x)$  must be terminated.

# 4.3 Supported ATA commands

The following table lists Serial ATA standard commands that the drive supports. For a detailed description of the ATA commands, refer to the Serial ATA: High Speed Serialized AT Attachment specification. See "S.M.A.R.T. commands" on page 46.for details and subcommands used in the S.M.A.R.T. implementation.

Table 16: Supported ATA commands

Command name	Command code (in hex)
Check Power Mode	98 <sub>H</sub> or E5 <sub>H</sub>
Device Configuration Freeze Lock	B1 <sub>H</sub> / C1 <sub>H</sub>
Device Configuration Identify	B1 <sub>H</sub> / C2 <sub>H</sub>
Device Configuration Restore	B1 <sub>H</sub> / C0 <sub>H</sub>
Device Configuration Set	B1 <sub>H</sub> / C3 <sub>H</sub>
Device Reset	08 <sub>H</sub>
Download Microcode	92 <sub>H</sub>
Execute Device Diagnostics	90 <sub>H</sub>
Flush Cache	E7 <sub>H</sub>
Flush Cache Extended	EA <sub>H</sub>
Format Track	50 <sub>H</sub>
Identify Device	EC <sub>H</sub>
Idle	97 <sub>H</sub> or E3 <sub>H</sub>
Idle Immediate	95 <sub>H</sub> or E1 <sub>H</sub>
Initialize Device Parameters	91 <sub>H</sub>
Read Buffer	E4 <sub>H</sub>
Read DMA	C8 <sub>H</sub>
Read DMA Extended	25 <sub>H</sub>
Read DMA Without Retries	C9 <sub>H</sub>
Read Log Ext	2F <sub>H</sub>
Read Multiple	C4 <sub>H</sub>
Read Multiple Extended	29 <sub>H</sub>
Read Native Max Address	F8 <sub>H</sub>
Read Native Max Address Extended	27 <sub>H</sub>
Read Sectors	20 <sub>H</sub>
Read Sectors Extended	24 <sub>H</sub>
Read Sectors Without Retries	21 <sub>H</sub>
Read Verify Sectors	40 <sub>H</sub>
Read Verify Sectors Extended	42 <sub>H</sub>
Read Verify Sectors Without Retries	41 <sub>H</sub>
Recalibrate	10 <sub>H</sub>
Security Disable Password	F6 <sub>H</sub>
Security Erase Prepare	F3 <sub>H</sub>

Command name	Command code (in hex)
Security Erase Unit	F4 <sub>H</sub>
Security Freeze	F5 <sub>H</sub>
Security Set Password	F1 <sub>H</sub>
Security Unlock	F2 <sub>H</sub>
Seek	70 <sub>H</sub>
Set Features	EF <sub>H</sub>
Set Max Address	F9 <sub>H</sub>
Note: Individual Set Max Address commands are identified by the value placed in the Set Max Features register as defined to the right.	Address: 00 <sub>H</sub> Password: 01 <sub>H</sub> Lock: 02 <sub>H</sub> Unlock: 03 <sub>H</sub> Freeze Lock: 04 <sub>H</sub>
Set Max Address Extended	37 <sub>H</sub>
Set Multiple Mode	C6 <sub>H</sub>
Sleep	99 <sub>H</sub> or E6 <sub>H</sub>
S.M.A.R.T. Disable Operations	B0 <sub>H</sub> / D9 <sub>H</sub>
S.M.A.R.T. Enable/Disable Autosave	B0 <sub>H</sub> / D2 <sub>H</sub>
S.M.A.R.T. Enable Operations	B0 <sub>H</sub> / D8 <sub>H</sub>
S.M.A.R.T. Execute Offline	B0 <sub>H</sub> / D4 <sub>H</sub>
S.M.A.R.T. Read Attribute Thresholds	B0 <sub>H</sub> / D1 <sub>H</sub>
S.M.A.R.T. Read Data	B0 <sub>H</sub> / D0 <sub>H</sub>
S.M.A.R.T. Read Log Sector	B0 <sub>H</sub> / D5 <sub>H</sub>
S.M.A.R.T. Return Status	B0 <sub>H</sub> / DA <sub>H</sub>
S.M.A.R.T. Save Attribute Values	B0 <sub>H</sub> / D3 <sub>H</sub>
S.M.A.R.T. Write Log Sector	B0 <sub>H</sub> / D6 <sub>H</sub>
Standby	96 <sub>H</sub> or E2 <sub>H</sub>
Standby Immediate	94 <sub>H</sub> or E0 <sub>H</sub>
Write Buffer	E8 <sub>H</sub>
Write DMA	CA <sub>H</sub>
Write DMA Extended	35 <sub>H</sub>
Write DMA FUA Extended	CD <sub>H</sub>
Write DMA Without Retries	CB <sub>H</sub>
Write Log Extended	3F <sub>H</sub>
Write Multiple	C5 <sub>H</sub>
Write Multiple Extended	39 <sub>H</sub>
Write Multiple FUA Extended	CE <sub>H</sub>
Write Sectors	30 <sub>H</sub>
Write Sectors Without Retries	31 <sub>H</sub>
Write Sectors Extended	34 <sub>H</sub>

## 4.3.1 Identify Device command

The Identify Device command (command code  $EC_H$ ) transfers information about the drive to the host following power up. The data is organized as a single 512-byte block of data, whose contents are shown in Table 16 on page 39. All reserved bits or words should be set to zero. Parameters listed with an "x" are drive-specific or vary with the state of the drive. See Section 2.0 on page 3 for default parameter settings.

The following commands contain drive-specific features that may not be included in the Serial ATA specification.

Word	Description	Value
0	Configuration information:  • Bit 15: 0 = ATA; 1 = ATAPI  • Bit 7: removable media  • Bit 6: removable controller  • Bit 0: reserved	0C5A <sub>H</sub>
1	Number of logical cylinders	16,383
2	ATA-reserved	0000 <sub>H</sub>
3	Number of logical heads	16
4	Retired	0000 <sub>H</sub>
5	Retired	0000 <sub>H</sub>
6	Number of logical sectors per logical track: 63	003F <sub>H</sub>
7–9	Retired	0000 <sub>H</sub>
10–19	Serial number: (20 ASCII characters, 0000 <sub>H</sub> = none)	ASCII
20	Retired	0000 <sub>H</sub>
21	Retired	0400 <sub>H</sub>
22	Obsolete	0000 <sub>H</sub>
23–26	Firmware revision (8 ASCII character string, padded with blanks to end of string)	x.xx
27–46	Drive model number: (40 ASCII characters, padded with blanks to end of string)	
47	(Bits 7–0) Maximum sectors per interrupt on Read multiple and Write multiple (16)	8010 <sub>H</sub>
48	Reserved	0000 <sub>H</sub>
49	Standard Standby timer, IORDY supported and may be disabled	2F00 <sub>H</sub>
50	ATA-reserved	0000 <sub>H</sub>
51	PIO data-transfer cycle timing mode	0200 <sub>H</sub>
52	Retired	0200 <sub>H</sub>
53	Words 54–58, 64–70 and 88 are valid	0007 <sub>H</sub>
54	Number of current logical cylinders	xxxx <sub>H</sub>
55	Number of current logical heads	xxxx <sub>H</sub>
56	Number of current logical sectors per logical track	xxxx <sub>H</sub>
57–58	Current capacity in sectors	xxxx <sub>H</sub>
59	Number of sectors transferred during a Read Multiple or Write Multiple command	xxxx <sub>H</sub>

Word	Description	Value
60-61	Total number of user-addressable LBA sectors available (see Section 2.2 for related information)  *Note: The maximum value allowed in this field is: 0FFFFFFFh (268,435,455 sectors, 137 Gbytes). Drives with capacities over 137 Gbytes will have 0FFFFFFh in this field and the actual number of user-addressable LBAs specified in words 100-103. This is required for drives that support the 48-bit addressing feature.	ST3500641AS = 0FFFFFFh* ST3500841AS = 0FFFFFFh* ST3400633AS = 0FFFFFFFh* ST3400833AS = 0FFFFFFFh* ST3320633AS = 0FFFFFFFh* ST3320833AS = 0FFFFFFFh* ST3300622AS = 0FFFFFFFh* ST3300822AS = 0FFFFFFFh* ST3250624AS = 0FFFFFFFh* ST3250824AS = 0FFFFFFFh* ST3250824AS = 0FFFFFFFh* ST3160812AS = 0FFFFFFFh* ST3160212AS = 0FFFFFFFh* ST3120813AS = 234,441,648 ST3120213AS = 234,441,648 ST3808110AS = 156,301,488 ST3802110AS = 156,301,488 ST3402111AS = 78,165,360
62	Retired	0000 <sub>H</sub>
63	Multiword DMA active and modes supported (see note following this table)	xx07 <sub>H</sub>
64	Advanced PIO modes supported (modes 3 and 4 supported)	0003 <sub>H</sub>
65	Minimum multiword DMA transfer cycle time per word (120 nsec)	0078 <sub>H</sub>
66	Recommended multiword DMA transfer cycle time per word (120 nsec)	0078 <sub>H</sub>
67	Minimum PIO cycle time without IORDY flow control (240 nsec)	00F0 <sub>H</sub>
68	Minimum PIO cycle time with IORDY flow control (120 nsec)	0078 <sub>H</sub>
69–74	ATA-reserved	0000 <sub>H</sub>
75	Queue depth	0000 <sub>H</sub>
76	Serial ATA capabilities	xxxx <sub>H</sub>
77	Reserved for future Serial ATA definition	xxxx <sub>H</sub>
78	Serial ATA features supported	xxxx <sub>H</sub>
79	Serial ATA features enabled	xxxx <sub>H</sub>
80	Major version number	003E <sub>H</sub>
81	Minor version number	0000 <sub>H</sub>
82	Command sets supported	364B <sub>H</sub>
83	Command sets supported	7C03 <sub>H</sub>
84	Command sets support extension	4003 <sub>H</sub>
85	Command sets enabled	30 <i>xx</i> <sub>H</sub>
86	Command sets enabled	0001 <sub>H</sub>
87	Command sets enable extension	4000 <sub>H</sub>
88	Ultra DMA support and current mode (see note following this table)	xx3F <sub>H</sub>
89	Security erase time	0000 <sub>H</sub>
90	Enhanced security erase time	0000 <sub>H</sub>

Word	Description	Value
92	Master password revision code	FFFE <sub>H</sub>
93	Hardware reset value (see description following this table)	xxxx <sub>H</sub>
95–99	ATA-reserved	0000 <sub>H</sub>
100- 103	Total number of user-addressable LBA sectors available (see Section 2.2 for related information). These words are required for drives that support the 48-bit addressing feature. Maximum value: 0000FFFFFFFFFh.	ST3500641AS = 976,773,168 ST3500841AS = 976,773,168 ST3400633AS = 781,422,768 ST3400833AS = 781,422,768 ST3320633AS = 625,142,448 ST3320833AS = 625,142,448 ST3300622AS = 586,072,368 ST3300822AS = 586,072,368 ST3250624AS = 488,397,168 ST3250824AS = 488,397,168 ST3200827AS = 390,721,968 ST3160812AS = 312,581,808 ST3160212AS = 312,581,808 ST3120813AS = 234,441,648 ST31808110AS = 156,301,488 ST3808110AS = 156,301,488 ST3402111AS = 78,165,360
104– 127	ATA-reserved	0000 <sub>H</sub>
128	Security status	0001 <sub>H</sub>
129– 159	Seagate-reserved	xxxx <sub>H</sub>
160- 254	ATA-reserved	0000 <sub>H</sub>
255	Integrity word	xxA5 <sub>H</sub>

Note. Advanced Power Management (APM) and Automatic Acoustic Management (AAM) features are not supported

**Note.** See the bit descriptions below for words 63, 88, and 93 of the Identify Drive data.

Description (if bit is set to 1)			
Bit	Word 63		
0	Multiword DMA mode 0 is supported.		
1	Multiword DMA mode 1 is supported.		
2	Multiword DMA mode 2 is supported.		
8	Multiword DMA mode 0 is currently active.		
9	Multiword DMA mode 1 is currently active.		
10	Multiword DMA mode 2 is currently active.		
Bit	Word 88		
0	Ultra DMA mode 0 is supported.		
1	Ultra DMA mode 1 is supported.		
2	Ultra DMA mode 2 is supported.		
3	Ultra DMA mode 3 is supported.		
4	Ultra DMA mode 4 is supported.		
5	Ultra DMA mode 5 is supported.		
6	Ultra DMA mode 6 is supported.		
8	Ultra DMA mode 0 is currently active.		
9	Ultra DMA mode 1 is currently active.		
10	Ultra DMA mode 2 is currently active.		
11	Ultra DMA mode 3 is currently active.		
12	Ultra DMA mode 4 is currently active.		
13	Ultra DMA mode 5 is currently active.		
14	Ultra DMA mode 6 is currently active.		

#### 4.3.2 Set Features command

This command controls the implementation of various features that the drive supports. When the drive receives this command, it sets BSY, checks the contents of the Features register, clears BSY and generates an interrupt. If the value in the register does not represent a feature that the drive supports, the command is aborted. Power-on default has the read look-ahead and write caching features enabled. The acceptable values for the Features register are defined as follows:

#### Table 17: Set Features command values

 $02_{H}$ Enable write cache (default). Set transfer mode (based on value in Sector Count register).  $03_{H}$ Sector Count register values: 00<sub>H</sub> Set PIO mode to default (PIO mode 2). 01<sub>H</sub> Set PIO mode to default and disable IORDY (PIO mode 2). 08<sub>H</sub> PIO mode 0 09<sub>H</sub> PIO mode 1 0A<sub>H</sub> PIO mode 2 0B<sub>H</sub> PIO mode 3 0C<sub>H</sub> PIO mode 4 (default) 20<sub>H</sub> Multiword DMA mode 0 21<sub>H</sub> Multiword DMA mode 1 22<sub>H</sub> Multiword DMA mode 2 40<sub>H</sub> Ultra DMA mode 0 41<sub>H</sub> Ultra DMA mode 1 42<sub>H</sub> Ultra DMA mode 2 43<sub>H</sub> Ultra DMA mode 3 44<sub>H</sub> Ultra DMA mode 4 45<sub>H</sub> Ultra DMA mode 5 46<sub>H</sub> Ultra DMA mode 6 10<sub>H</sub> Enable use of SATA features Disable read look-ahead (read cache) feature. 55<sub>H</sub> 82<sub>H</sub> Disable write cache 90<sub>H</sub> Disable use of SATA features

Enable read look-ahead (read cache) feature (default).

Report full capacity available

**Note.** At power-on, or after a hardware or software reset, the default values of the features are as indicated above.

 $AA_H$ 

F1<sub>H</sub>

#### 4.3.3 S.M.A.R.T. commands

S.M.A.R.T. provides near-term failure prediction for disc drives. When S.M.A.R.T. is enabled, the drive monitors predetermined drive attributes that are susceptible to degradation over time. If self-monitoring determines that a failure is likely, S.M.A.R.T. makes a status report available to the host. Not all failures are predictable. S.M.A.R.T. predictability is limited to the attributes the drive can monitor. For more information on S.M.A.R.T. commands and implementation, see the *Draft ATA-5 Standard*.

SeaTools diagnostic software activates a built-in drive self-test (DST S.M.A.R.T. command for D4<sub>H</sub>) that eliminates unnecessary drive returns. The diagnostic software ships with all new drives and is also available at: <a href="http://seatools.seagate.com">http://seatools.seagate.com</a>.

This drive is shipped with S.M.A.R.T. features disabled. You must have a recent BIOS or software package that supports S.M.A.R.T. to enable this feature. The table below shows the S.M.A.R.T. command codes that the drive uses.

Table 18: S.M.A.R.T. commands

Code in features register	S.M.A.R.T. command
D0 <sub>H</sub>	S.M.A.R.T. Read Data
D2 <sub>H</sub>	S.M.A.R.T. Enable/Disable Attribute Autosave
D3 <sub>H</sub>	S.M.A.R.T. Save Attribute Values
D4 <sub>H</sub>	S.M.A.R.T. Execute Off-line Immediate (runs DST)
D5 <sub>H</sub>	S.M.A.R.T. Read Log Sector
D6 <sub>H</sub>	S.M.A.R.T. Write Log Sector
D8 <sub>H</sub>	S.M.A.R.T. Enable Operations
D9 <sub>H</sub>	S.M.A.R.T. Disable Operations
DA <sub>H</sub>	S.M.A.R.T. Return Status

**Note.** If an appropriate code is not written to the Features Register, the command is aborted and 0x04 (abort) is written to the Error register.

# 5.0 Seagate Technology support services

#### Internet

For information regarding Seagate products and services, visit <u>www.seagate.com</u>. Worldwide support is available 24 hours daily by email for your questions.

### **Presales Support:**

Presales@Seagate.com

### **Technical Support:**

DiscSupport@Seagate.com

### **Warranty Support:**

http://www.seagate.com/support/service/index.html

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### **Technical Support**

Seagate technical support is available to assist you online at <u>support.seagate.com</u> or through one of our call centers. Have your system configuration information and your "ST" model number available.

**SeaTDD™** (+1-405-324-3655) is a telecommunications device for the deaf (TDD). You can send questions or comments 24 hours daily and exchange messages with a technical support specialist during normal business hours for the call center in your region.

## **Customer Service Operations**

### **Warranty Service**

Seagate offers worldwide customer support for Seagate products. Seagate distributors, OEMs and other direct customers should contact their Seagate Customer Service Operations (CSO) representative for warranty-related issues. Resellers or end users of drive products should contact their place of purchase or Seagate warranty service for assistance. Have your serial number and model or part number available.

### **Data Recovery Services**

Seagate offers data recovery services for all formats and all brands of storage media. Our data recovery services labs are currently located throughout the world. Additional information, including an online request form and data loss prevention resources, is available at <a href="http://services.seagate.com/index.aspx">http://services.seagate.com/index.aspx</a>

#### **Authorized Service Centers**

Seagate Service Centers are available on a global basis for the return of defective products. Contact your customer support representative for the location nearest you.

## **USA/Canada/Latin America support services**

For an extensive list of telephone numbers to technical support, presales and warranty service in USA/ Canada/Latin America, including business hours, go to the "Contact Us" page on <a href="https://www.seagate.com">www.seagate.com</a>.

## **Global Customer Support**

Presales, Technical, and Warranty Support

Call Center Toll-free Direct dial

USA, Canada,

and Mexico 1-800-SEAGATE +1-405-324-4700

**Data Recovery Services** 

Call Center Toll-free Direct dial FAX

USA, Canada, 1-800-475-01435 +1-905-474-2162 1-800-475-0158 and Mexico +1-905-474-2459

## **Europe, the Middle East and Africa Support Services**

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